

Max van 't Hart

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Education

MSc	TU Delft , High-Tech Engineering	Delft, Netherlands 2022 – present
BSc	TU Delft , Mechanical Engineering - Completed a Robotics minor, including the design and development of the "Mason" autonomous jointing robot - Completed my graduation project at the Cognitive Robotics department, developing a lab-cleanup robot based on the MIRTE Master Platform	Delft, Netherlands 2022 – 2026
BSc	TU Delft , Applied Physics Started in Applied Physics before switching to Mechanical Engineering	Delft, Netherlands 2021 – 2022
VWO	RSG Brokdele , Nature & Technology - N&T subject package with Economics and Nature, Life and Technology (NLT) - Completed my VWO graduation project by designing and building a functional railgun	Breukelen, Netherlands 2015 – 2021

Experience

RoBoHouse , Lead Mechanical Engineer	Delft, Netherlands June 2025 – Dec 2025 7 months
- Led the mechanical engineering work within the multidisciplinary in-house SUSAG project - Designed, developed, and manufactured a fully functional unmanned ground vehicle (UGV)	
Picnic , Delivery Driver	Utrecht, Netherlands Feb 2021 – Aug 2023 2 years 7 months
- Delivered groceries in and around Utrecht - Gained extensive driving and customer-service experience	
Notary Office , Employee	Maarssen, Netherlands May 2022 – Aug 2022 4 months
Assisted with the processing of sensitive information	
Albert Heijn , Store Employee	Maarssen, Netherlands Dec 2018 – present 7 years 9 months
- Worked for several years in the fruit and vegetable department - Regularly assisted customers with questions and product requests	

Projects

Custom High-Performance E-Bikes	2021 – present
- Designed and built custom e-bikes for myself and family members - Developed skills in soldering, CAD, programming, 3D printing, and bicycle mechanics - Progressed from simple off-the-shelf electronics to systems based on the open-source VESC platform	
Mason	2024 – 2025
- Developed a robotic system for SMB Geveltechniek with a team of six students during a Robotics minor - Robot was designed to scan brick walls using a stereo camera, apply jointing material, and clean the wall afterwards - Responsible for designing and producing most of the robot's movement systems	

GreenRocket • Built a seed-planting robot with four other students for the Boskalis Hackathon hosted by the TU Delft Robotics Student Association • The project won the hackathon	2025 – 2025
PijpMasterPro6000 • Designed and built a pipe-navigating robot with four other students for the Underground Robotics Hackathon hosted by the TU Delft Robotics Student Association • The team placed second in the hackathon	2025 – 2025
Custom Lightweight Gaming Mice • Designed custom modification kits that convert existing gaming mice into lightweight high-performance designs • Started as a personal project and developed into selling modification kits online	2024 – present
Custom Car Audio System • Built a custom sound system for a car together with my brother • Reverse engineered existing components and designed custom parts to install larger speakers in the original locations	2025 – 2025
Railgun • Built a functioning railgun with another student as a VWO final project • Used an approximately 450 V high-voltage capacitor bank and electromagnetic acceleration • Designed and programmed supporting electronics using Arduino and later ESP32 hardware	2021 – 2021

Awards

Boskalis Hackathon Winner • Built the winning GreenRocket seed-planting robot with a team of students	Jan 2025
Certified SOLIDWORKS Professional (CSWP)	Jan 2024
Green Award • Awarded for incorporating topology optimization into the team's first-year engineering project	Jan 2023

Skills

CAD: SOLIDWORKS, Certified SOLIDWORKS Professional (CSWP)

Prototyping: 3D printing, soldering, mechanical assembly

Programming: Python

Engineering: Mechanical design, electronics, rapid prototyping

Interests

Engineering: Robotics, mechanical design, electronics, 3D printing

Automotive: Cars, bicycles, vehicle technology

Technology: Computers and gaming hardware